

HT6026 Remote Control Encoder

Features

- Operating voltage: 4V~18V
- Low standby current
- Low power and high noise immunity CMOS technology 3° different
- different codes

- Minimum of two transmission words Built-in oscillator needs only 5% resistor
- Interface with RF or infrared transmission medium
- Minimal external components

Applications

- Burglar alarm system
- Smoke and fire alarm system
- Garage door controllers
- Car alarm system

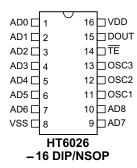
- Security system
- Cordless telephones
- Other remote control systems

General Description

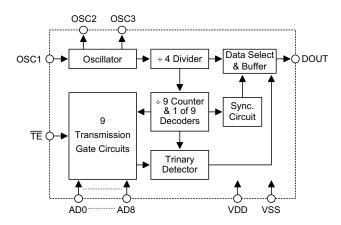
The HT6026 is a CMOS LSI encoder designed for remote control system applications. It is capable of encoding 9 bits of information which consists of N address bits and 9-N data bits. Each address/data input is externally trinary programmable by external switches. The programmable

address/data is transmitted along with the header bits via an RF or an infrared transmission medium upon receipt of a trigger signal ($\overline{\text{TE}}$).

Pin Assignment



Block Diagram



Unit: $\mu \textbf{\textit{m}}$



Pad Coordinates

		VDD AD0	DOUT	핆	
AD1	1	16 15	14	13	
AD2	2				
AD3	3		0,0)	12	OSC3
AD4	4	ı	-	_	
AD5	5			11	OSC2
AD6	6	7 8	9	10	OSC1
		AD7	AD8		

Pad No.	X	Y	Pad No.	X	Y
1	-598.00	689.00	9	160.00	-687.00
2	-674.00	433.00	10	670.00	-687.00
3	-674.00	126.00	11	670.00	-347.00
4	-674.00	-162.00	12	670.00	172.00
5	-674.00	-449.00	13	670.50	689.50
6	-598.00	-687.00	14	270.00	689.00
7	-342.00	-687.00	15	-84.00	689.00
8	-127.00	-687.00	16	-299.00	689.00

Chip size: $1650 \times 1680 \; (\mu m)^2$

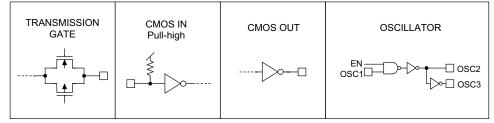
Pin Description

Pin No.	Pin Name	I/O	Internal Connection	Description		
1~7	AD0~AD6	I	TRANSMISSION GATE	Input pins for address/data AD0~AD6 setting. They can be externally set to VDD, VSS, or left open.		
8	VSS	I	_	Negative power supply (GND)		
9~10	AD7~AD8	I	TRANSMISSION GATE	Input pins for address/data AD7~AD8 setting. They can be externally set to VDD, VSS, or left open.		
11	OSC1	Ι	OSCILLATOR	Oscillator input pin		
12	OSC2	О	OSCILLATOR	Oscillator output pin		
13	OSC3	О	OSCILLATOR	Oscillator output pin		
14	$\overline{ ext{TE}}$	I	CMOS IN Pull-high	Transmission enable, active low		
15	DOUT	О	CMOS OUT	Encoder data serial transmission output		
16	VDD		_	Positive power supply		

 $[\]mbox{\ensuremath{^{\star}}}$ The IC substrate should be connected to VSS in the PCB layout artwork.



Approximate internal connection circuits



Absolute Maximum Ratings

Supply Voltage0.3V to 24V	Storage Temperature -50° C to 125° C
Input Voltage V_{SS} -0.3 to V_{DD} +0.3V	Operating Temperature20°C to 75°C

Note: These are stress ratings only. Stresses exceeding the range specified under "Absolute Maximum Ratings" may cause substantial damage to the device. Functional operation of this device at other conditions beyond those listed in the specification is not implied and prolonged exposure to extreme conditions may affect device reliability.

Electrical Characteristics

Ta=25°C

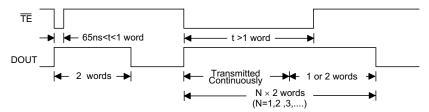
Cb al	D (Test Conditions	ъл:	Тур.	Max.	Unit
Symbol	Parameter	V_{DD}	Conditions	Min.			
$V_{ m DD}$	Operating Voltage	_		4	_	18	V
Lown	I G N G		Ossillatan atau a		0.1	0.3	μΑ
I _{STB}	Standby Current	15V	Oscillator stops		0.1	0.5	μΑ
T	I 0 0		No load, f _{OSC} =18kHz		500	900	μA
I_{DD}	Operating Current	15V	No load, f_{OSC} =22kHz		2000	3000	μΑ
		5V	V0 0V (Course)	-1.0	-1.7	_	mA
T	Out and Dail of Comment	15V	V{OH} =0.9 V_{DD} (Source)	-8.0	-14.0		mA
$I_{ m DOUT}$	Output Drive Current	5V	V =0.1V (Cinla)	0.8	1.5		mA
		15V	$V_{\rm OL}$ =0.1 $V_{ m DD}$ (Sink)	5.0	10.0		mA
V _{IH}	"H" Input Voltage		_	$0.7V_{ m DD}$		Vdd	V
$V_{\rm IL}$	"L" Input Voltage	_	_	0		$0.3V_{ m DD}$	V
р—	<u>me</u> b 111; 1 b ; 4	5V	V—-0V		800		kΩ
$R_{\overline{TE}}$	TE Pull-high Resistance	15V	$V_{\overline{ ext{TE}}}$ =0 V		250		kΩ
forg	Oscillator Fraguence	5V	$R_{EXT}=10k\Omega$		18	_	kHz
f_{OSC}	Oscillator Frequency	15V	$ m C_{EXT}$ =2000PF $ m R_{S}$ =20k $ m \Omega$	_	22		kHz



Functional Description

Operation

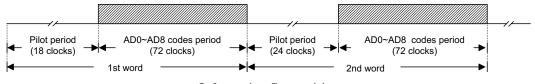
The HT6026 encoder begins a one-word transmission cycle upon receipt of a transmission enable ($\overline{\text{TE}}$, active low). This cycle will repeat itself as long as the transmission enable ($\overline{\text{TE}}$) is held low. Once the transmission enable returns high, the encoder output completes its final N×2 word cycle, and then stops as shown in the Transmission timing diagram below. The total number of transmission cycles allowed is always automatically adjusted to an even number.



Transmission timing

Information word

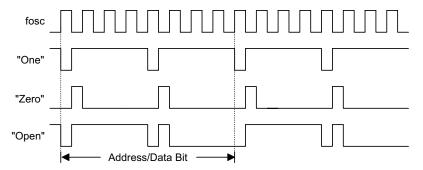
An information word consists of two periods as shown:



Information Composition

Address/data waveform

Each programmable address/data pin can be externally set to one of the following three logic states:



Address/Data bit waveform

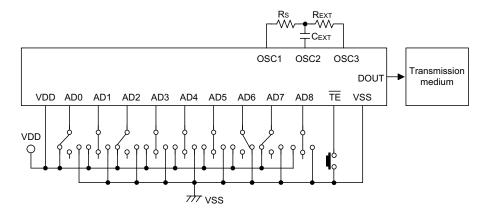


Address/data programming (preset)

The status of each address/data pin can be individually preset to logic "high", "low", or "floating". If a transmission enable signal is applied, the encoder scans and transmits the status of the 9-bit address/data serially in the order AD0 to AD8. But if the trigger signal is not applied, the chip only consumes a standby current which is less than $1\mu A$ (for VDD=5V).

The address pins are usually preset to transmit data codes with their own particular security codes by the DIP switches or PCB wiring, while the data is selected using push buttons or electronic switches.

The following figure demonstrates an application using the HT6026:



The transmitted information is as listed:

Pilot &	AD0	AD1	AD2	AD3	AD4	AD5	AD6	AD7	AD8
Sync.	1	Z	1	Z	Z	Z	0	1	Z

Z: floating

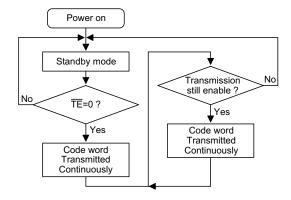
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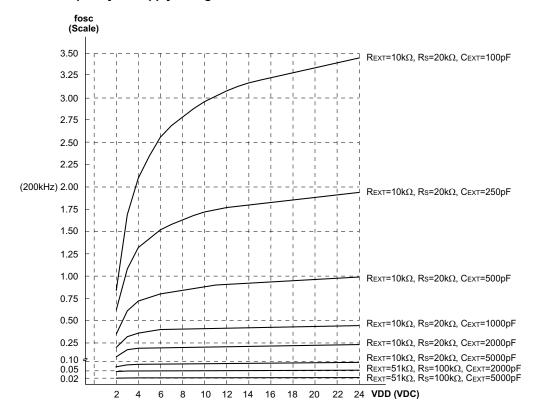
Transmission enable

Transmission is enabled by applying a low signal to the \overline{TE} pin. The HT6026 is enabled and outputs address/data codes from the DOUT pin when \overline{TE} is set to "low" for more than 65ns.

Flowchart

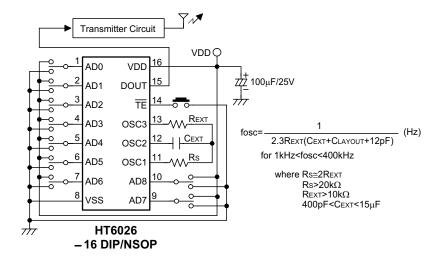


Oscillator frequency vs supply voltage





Application Circuit





Holtek Semiconductor Inc. (Headquarters)

No.3, Creation Rd. II, Science Park, Hsinchu, Taiwan Tel: 886-3-563-1999 Fax: 886-3-563-1189 http://www.holtek.com.tw

Holtek Semiconductor Inc. (Taipei Sales Office)

4F-2, No. 3-2, YuanQu St., Nankang Software Park, Taipei 115, Taiwan

Tel: 886-2-2655-7070 Fax: 886-2-2655-7373

 $Fax: 886\text{-}2\text{-}2655\text{-}7383 \ (International \ sales \ hotline)$

Holtek Semiconductor Inc. (Shanghai Sales Office)

7th Floor, Building 2, No.889, Yi Shan Rd., Shanghai, China 200233 Tel: 021-6485-5560

Fax: 021-6485-0313 http://www.holtek.com.cn

Holtek Semiconductor Inc. (Shenzhen Sales Office)

43F, SEG Plaza, Shen Nan Zhong Road, Shenzhen, China 518031

Tel: 0755-8346-5589 Fax: 0755-8346-5590 ISDN: 0755-8346-5591

Holtek Semiconductor Inc. (Beijing Sales Office)

Suite 1721, Jinyu Tower, A129 West Xuan Wu Men Street, Xicheng District, Beijing, China 100031

Tel: 010-6641-0030, 6641-7751, 6641-7752

Fax: 010-6641-0125

Holmate Semiconductor, Inc. (North America Sales Office)

46712 Fremont Blvd., Fremont, CA 94538 Tel: 510-252-9880 Fax: 510-252-9885 http://www.holmate.com

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